# Michael A. Kokko

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#### Education

Ph.D.	Engineering Science. Thayer School of Engineering at Dartmouth College. <i>Expected 2021</i> . Advisors: Douglas W. Van Citters, PhD and Ryan J. Halter, PhD Thesis topic: "A Framework for Navigated Organ Exposure in Robotic Laparoscopy"
S.M.	Mechanical Engineering. Massachusetts Institute of Technology, 2007. Thesis: "Range-based Navigation of AUVs Operating Near Ship Hulls" Advisors: John J. Leonard, PhD and Franz S. Hover, PhD
B.S.	Mechanical Engineering. Rensselaer Polytechnic Institute, 2005.

#### **Professional Experience**

٠	Graduate Research Assistant – Thayer School of Engineering, Dartmouth College – Hanover, NH	2016 – present
•	Sr. Systems Integration Engineer – Simbex, LLC. – Lebanon, NH	2011 – 2016
٠	Robotics Engineer – Vecna Technologies – Cambridge, MA	2007 – 2011
•	Graduate Research Assistant – MIT Marine Robotics Laboratory – Cambridge, MA	2005 – 2007
٠	Undergraduate Researcher – RPI Flexible Manufacturing Center – Troy, NY	2003 – 2005

#### **Teaching Experience**

- Lecturer Dartmouth ENGS 72 Dynamics (Primary instructor, reworked and delivered all 34 lectures) Fall 2019
- Lead Teaching Assistant Dartmouth ENGS 72 Dynamics (Ran problem sessions, delivered 4 lectures) Fall 2018
- Lead Teaching Assistant Dartmouth ENGS 72 Dynamics (Ran problem sessions, delivered 5 lectures) Fall 2017
- Lead Teaching Assistant Dartmouth ENGS 72 Dynamics (Ran problem sessions, delivered 3 lectures) Fall 2016

# Academic Talks and Invited Classroom Lectures

- "Navigating in the Abdomen." Dartmouth Engineering in Medicine Lecture Series. January 11, 2019.
- "Racing Against Bacteria: An Engineering Perspective on Infection." Dartmouth ENGS 165. Spring 2018-2020
- "Pushing the Limit (Cycle): Nonlinear Dynamics and Limit Cycle Analysis in Biomedical Engineering." Dartmouth Engineering in Medicine Lecture Series. December 1, 2017.
- "How Good Is My Diagnostic Test?" Dartmouth Engineering In Medicine Lecture Series. April 28, 2017.
- "Medicare and Medical Devices." Dartmouth ELEC 178 Medical Device Design Elective. April 11, 2017.
- "Considerations for Developing Medical Devices." Dartmouth ENGS 57/169. April 9, 2015.

# Awards and Honors

٠	Citations for superior teaching assistant performance (Dartmouth ENGS 72 Applied Dynamics)	2016, 2017, 2018
•	Outstanding Poster Award - Dartmouth Graduate Student Poster Session	2018
•	Arthur M. Greene Prize – Rensselaer Polytechnic Institute	2005
•	4.0 Certificate – Rensselaer Polytechnic Institute	2005
•	Founders' Award – Rensselaer Polytechnic Institute	2003
•	Rensselaer Medal Scholarship	2001

#### Service

• Volunteer Appalachian Trail Boundary Monitor (section of Kodak Trail on Mt. Cube, Orford, NH) 2018 – present

• Reviewer for TREAT (NIH funded) and NEPDC (FDA funded) technology commercialization grants 2014 – 2019

• Emergency Department Volunteer – Dartmouth-Hitchcock Medical Center (~3hrs/wk, year-round) 2011 – 2016

•	Winter School Trip Leader – MIT Outing Club	2005 – 2014
•	FIRST Robotics Mentor – Cambridge Rindge and Latin School	2005

# **Mentorship and Advising**

•	Sophomore Scholar Mentor: Joselyn Lopez RALPN phantom development	2020
٠	ENGS 89/90 Senior Capstone Advisor: Drone-based cremains dispersal mechanism	2019 – 2020
٠	ENGS 89/90 Senior Capstone Advisor: Drone-based microplate transport gripper	2019 – 2020
٠	Simbex Co-op Mentor: Conor McKaig (RIT); medical mattress valve replacement and system testing	2015
٠	Simbex Co-op Mentor: Linzey Miller (RIT); helmet sensor durability, IMU evaluation	2014
•	Simbex Co-op Mentor: Mireille Kelley (UConn); blast dosimeter fitting, reflex air cannon	2013
•	Simbex Co-op Mentor: Jon Roth (Cornell); helmet sensor characterization	2012

# Patents

•	Two patents pending on technologies for pressure-reducing medical support surfaces (Simbex)	2019
•	US 8739820 B1 "Pressure Relief Valve" (with Daniel Theobald, Vecna Technologies)	2014

# **Professional Society Memberships**

•	American Society for Engineering Education (ASEE), Student Member	2019 – present
٠	International Society for Optics and Photonics (SPIE), Student Member	2018 – present
•	Orthopedic Research Society (ORS), Student Member	2018
٠	Institute for Electrical and Electronic Engineers (IEEE), Student Member (EMBS, RAS)	2016 – present
٠	ANSI/RESNA Support Surface Standards Initiative Committee (Representative of Simbex)	2014 – 2015

#### **Grant Funding**

 Norris Cotton Cancer Center Pilot Grant (\$50k). *Grant author*. PI: Ryan J. Halter. 2018 – 2020 "Anatomical Modeling for Real-Time Guidance in RALPN Organ Access"

# **Technical Skills**

- Engineering team & project management: planning, execution, verification/validation, and delivery
- Mechanical system design involving electric and hydraulic actuation, power transmission, bearing selection, and seal design with emphasis on manufacturability and assembly
- Extensive knowledge of design software: SolidWorks, MATLAB/Octave, basic FEA and dynamic simulation
- Broad mechanical fabrication experience: precision manual milling and turning, CNC machining, welding and brazing; working knowledge of injection molding, rapid prototyping, industrial robotics, and metrology
- Electrical prototyping involving analog and digital circuit design, embedded system development, PCB layout, serial communication, and circuit analysis using oscilloscope and other standard test equipment
- System integration, wiring, and troubleshooting/resolution of electromechanical issues
- Embedded and object-oriented programming in C/C++ with knowledge of Java, Perl, and Python; adept at most general computing tasks under both Windows and Linux environments
- Professional communication including written and oral presentation of design information and analyses

# Publications

• Kokko MA and Chapman RM. Gyroscope-Based Measurement of Tibia Coronal Alignment in Total Knee Arthroplasty. *In review.* 

- Kokko MA, Abdel MP, Berry DJ, Butler RD, Van Citters DW. A retrieval analysis perspective on revision for infection. Arthroplasty Today 2019; 5(3), 359-367. doi: <u>10.1016/j.artd.2019.03.007</u>
- Kokko MA. Range-based navigation of AUVs operating near ship hulls. S.M. Thesis, Mechanical Engineering, Massachusetts Institute of Technology, Cambridge, MA, 2007. doi: <u>1721.1/40292</u>

# **Conference Presentations and Proceedings**

- Kokko, MA, Seigne JD, Van Citters DW, Halter RJ. Multi-body statistical shape representation of anatomy for navigation in Robot-Assisted Laparoscopic Partial Nephrectomy. SPIE Medical Imaging Symposium 2021.
  Accepted as a podium presentation at: SPIE Medical Imaging, 2021 Feb 14-28; San Diego, CA.
- Kokko, MA, Seigne JD, Van Citters DW, Halter RJ. Development of exposure phase navigation as a training aid in robotic surgery. *Poster presentation* at: National Image Guided Therapy Virtual Workshop, 2020 Apr 16; Rockville, MD. Recording available: <u>https://youtu.be/sg3ytCMeHP0</u>
- Kokko, MA, Seigne JD, Van Citters DW, Halter RJ. Modeling the surgical exposure of anatomy in robot-assisted laparoscopic partial nephrectomy. SPIE Medical Imaging Symposium 2020. *Podium presentation* at: SPIE Medical Imaging, 2020 Feb 15-20; Houston, TX. doi: <u>10.1117/12.2550605</u>
- Kokko MA, Seigne JD, Van Citters DW, Halter RJ. Toward a framework for navigational guidance during surgical access. SPIE Medical Imaging Symposium 2019. *Poster presentation* at: SPIE Medical Imaging, 2019 Feb 16-21; San Diego, CA. doi: <u>10.1117/12.2513040</u>
- Kokko MA, Abdel MP, Berry DJ, Butler RD, Van Citters DW. When does PJI strike? A retrieval analysis perspective. *Podium presentation* at: Orthopedic Research Society annual meeting; 2018 Mar 10-13; New Orleans, LA.
- Kokko MA, Halter RJ, Van Citters DW. Bioimpedance of synovial fluid in a series of osteoarthritic knees. *Poster presentation* at: Orthopedic Research Society annual meeting; 2018 Mar 10-13; New Orleans, LA.
- Mayer LW, **Kokko MA**, Halter RJ, Van Citters, DW. Synthesis of an electrical analog for synovial fluid of the human knee. *Poster presentation* at: Orthopedic Research Society annual meeting; 2018 Mar 10-13; New Orleans, LA.
- Kokko MA and Hover FS. Estimating vehicle position using few range measurements to a known curved surface. Field and Service Robotics: Results of the 6th International Conference, C. Laugier and R. Siegwart, eds., pp. 223-232, Berlin, Heidelberg: Springer Berlin Heidelberg, 2008. *Podium presentation*. doi: <u>10.1007/978-3-540-75404-6\_21</u>
- Vaganay J, Elkins ML, Esposito D, Hover FS, **Kokko MA.** Ship Hull Inspection with the HAUV: US Navy and NATO Demonstrations Results. OCEANS 2006, Boston, MA, 2006, pp. 1-6. doi: <u>10.1109/OCEANS.2006.307039</u>

# **Other Workshops**

• 2018 Hamlyn Winter School for Surgical Imaging and Vision. Imperial College London. 2018 DEC 02-08. *Participant.* Runner-up for best group project on deep learning to identify needles in ultrasound.